

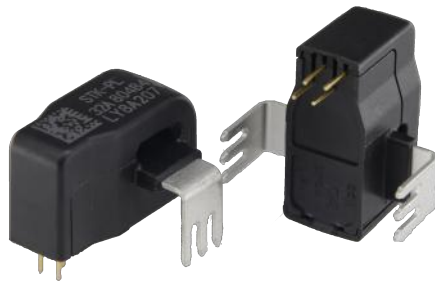
## Current Sensor

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Product Series: STK-PL/AG

Part number: STK-10PL/AG  
STK-20PL/AG  
STK-32PL/AG  
STK-40PL/AG  
STK-50PL/AG

Version: Ver 3.0



Sinomags Technology Co., Ltd

Web site: [www.sinomags.com](http://www.sinomags.com)

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## 1. Summary

The STK-PL/AG series is based on TMR (Tunneling-Magnetoresistance) technology and open-loop design. It is suitable for DC, AC, pulsed and any kind of irregular current measurement under the isolated conditions. The nominal current range of the STK-PL/AG current sensor consists of 10 A, 20 A, 32 A, 40 A, 50 A.

### Typical applications

- PV combiner box
- PV inverter (MPPT & AC)
- motor driver controller
- SMPS & UPS
- Battery management system

### Standards

- EN50178:1997
- IEC 61010-1:2010
- IEC 61326-1:2012

### General parameter

Parameter	Symbol	Unit	Value
Working temperature	T <sub>A</sub>	°C	-40 ~ 105
Storage temperature	T <sub>stg</sub>	°C	-40 ~ 105
Mass	m	g	10
Current line impedance	Z	mΩ	0.2
Current line temperature rise	Tr	°C	110

### Absolute maximum rating

Parameter	Symbol	Unit	Value
Supply voltage (non-destructive)	V <sub>C</sub>	V	6.0
ESD rating (HBM)	U <sub>ESD</sub>	kV	4
ESD rating (CDM)	U <sub>CDM</sub>	kV	1.5

Remark: the unrecoverable damage may occur when the product works on the conditions over the absolute maximum ratings. Long-time working on the absolute maximum ratings may cause the degradation on performance and reliability.

**Ratings**

Parameter	Symbol	Unit	Value
Primary involved potential		V AC/DC	600
Ambient operating temperature	T_A	°C	105
Primary current	I_p	A	According to series primary current
Secondary supply voltage	U_c	V DC	5
Output voltage	V_out	V	0.1 ~ 4.9

**Isolation parameter**

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC test 50Hz/1 min	U <sub>d</sub>	kV	5	
Impulse withstand voltage 1.2/50μs	Ū <sub>w</sub>	kV	8	
Clearance distance (pri. -sec)	d <sub>Cl</sub>	mm	8	Shortest distance through air
Creepage distance (pri. -sec)	d <sub>Cp</sub>	mm	8	Shortest path along device body
Case material			V0 according to UL 94	
Application example		V	600	Reinforced insulation, CAT III, PD 2, non uniform field according EN 50178, IEC 61010
Application example		V	1000	Basic insulation, CAT III, PD 2, non uniform field according EN 50178, IEC 61010
Application example		V	1500	Basic insulation, CAT III, PD 2, according to IEC 62109-1 Altitude ≤ 3000 m
Application example		V	600	CAT III, PD 2, according to UL 508

## 2. STK-10PL/AG Electrical performance

Condition:  $T_A = 25^\circ\text{C}$ ,  $V_{cc} = 5\text{ V}$  (Except special instructions)

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal current rms	$I_{pn}$	A		10		
Primary current measuring range	$I_{pm}$	A	-25		25	
Supply voltage	$V_{cc}$	V	4.75	5	5.25	
Current consumption	$I_{cc}$	mA		5	10	
Reference voltage	$V_{ref}$	V	2.48	2.5	2.52	Output function
Rated output voltage	$V_{FS}$	V		0.8		$(V_{out} - V_{ref}) @ I_{pn}$
Internal output resistance	$R_{out}$	$\Omega$		1		Output
Internal output resistance	$R_{ref}$	$\Omega$		1		Output
Quiescent voltage	$V_{off}$	V	2.48	2.5	2.52	$V_{out} @ 0\text{ A}$
Electrical offset voltage	$V_{oe}$	mV	-10		10	$(V_{out} - V_{ref}) @ 0\text{ A}$
Temperature drift of $V_{oe}$	$V_{oe\_TRange}$	mV	-8		8	$-40^\circ\text{C} \sim 105^\circ\text{C}$
Magnetic offset current	$I_{om}$	A	-0.25		0.25	@ $\pm 10 \times I_{pn}$
Theoretical gain	$G_{th}$	mV/A		80		800 mV @ $I_{pn}$
Error of gain	$Err\_G$	% $G_{th}$		$\pm 0.5$		Trimmed in the factory @ $25^\circ\text{C}$
Temperature drift of gain	$G_{TR}$	% $G_{th}$	-1.0		1.0	$-40^\circ\text{C} \sim 105^\circ\text{C}$
Rated linearity error	$Non-L_{pn}$	% $I_{pn}$	-0.5		0.5	$\pm I_{pn}$
Linearity error @ $I_{pm}$	$Non-L_{pm}$	% $I_{pm}$	-1		1	$\pm I_{pm}$
Reaction time	$t_{ra}$	$\mu\text{s}$		0.1	0.2	@ 10% of $I_{pn}$
Step response time	$t_{res}$	$\mu\text{s}$		0.2	0.5	@ 90% of $I_{pn}$
Delay time	$t_{delay}$	$\mu\text{s}$		0.2		1000kHz sine wave
Frequency bandwidth (-3dB)	BW	kHz		1000		No RC circuit
Output voltage noise	$V_{noise}$	mVpp		15		
DC ~ 10 kHz				25		
DC ~ 100 kHz						
Accuracy @ $25^\circ\text{C}$	X	% of $I_{pn}$	-1		1	@ $25^\circ\text{C}$
Accuracy @ $-40^\circ\text{C} \sim 105^\circ\text{C}$	$X_{TRange}$	% of $I_{pn}$	-2		2	$-40^\circ\text{C} \sim 105^\circ\text{C}$

### 3. STK-20PL/AG Electrical performance

 Condition:  $T_A = 25^\circ\text{C}$   $V_{cc} = 5\text{V}$  (Except special instructions)

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal current rms	$I_{pn}$	A		20		
Primary current measuring range	$I_{pm}$	A	-50		50	
Supply voltage	$V_{cc}$	V	4.75	5	5.25	
Current consumption	$I_{cc}$	mA		5	10	
Reference voltage	$V_{ref}$	V	2.48	2.5	2.52	Output function
Rated output voltage	$V_{FS}$	V		0.8		$(V_{out} - V_{ref}) @ I_{pn}$
Internal output resistance	$R_{out}$	$\Omega$		1		Output
Internal output resistance	$R_{ref}$	$\Omega$		1		Output
Quiescent voltage	$V_{off}$	V	2.48	2.5	2.52	$V_{out} @ 0\text{A}$
Electrical offset voltage	$V_{oe}$	mV	-10		10	$(V_{out} - V_{ref}) @ 0\text{A}$
Temperature drift of $V_{oe}$	$V_{oe\_TRange}$	mV	-8		8	$-40^\circ\text{C} \sim 105^\circ\text{C}$
Magnetic offset current	$I_{om}$	A	-0.25		0.25	@ $\pm 10 \times I_{pn}$
Theoretical gain	$G_{th}$	mV/A		40		800 mV @ $I_{pn}$
Error of gain	$Err\_G$	% $G_{th}$		$\pm 0.5$		Trimmed in the factory @ $25^\circ\text{C}$
Temperature drift of gain	$G_{TR}$	% $G_{th}$	-1.0		1.0	$-40^\circ\text{C} \sim 105^\circ\text{C}$
Rated linearity error	$Non-L_{pn}$	% $I_{pn}$	-0.5		0.5	$\pm I_{pn}$
Linearity error @ $I_{pm}$	$Non-L_{pm}$	% $I_{pm}$	-1		1	$\pm I_{pm}$
Reaction time	$t_{ra}$	$\mu\text{s}$		0.1	0.2	@ 10% of $I_{pn}$
Step response time	$t_{res}$	$\mu\text{s}$		0.2	0.5	@ 90% of $I_{pn}$
Delay time	$t_{delay}$	$\mu\text{s}$		0.2		1000kHz sine wave
Frequency bandwidth (-3dB)	BW	kHz		1000		No RC circuit
Output voltage noise	$V_{noise}$	mVpp		12		
DC ~ 10 kHz				17		
DC ~ 100 kHz						
Accuracy @ $25^\circ\text{C}$	X	% of $I_{pn}$	-1		1	@ $25^\circ\text{C}$
Accuracy @ $-40^\circ\text{C} \sim 105^\circ\text{C}$	$X_{TRange}$	% of $I_{pn}$	-2		2	$-40^\circ\text{C} \sim 105^\circ\text{C}$

#### 4. STK-32PL/AG Electrical performance

Condition:  $T_A = 25^\circ\text{C}$   $V_{cc} = 5\text{V}$  (Except special instructions)

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal current rms	I <sub>pn</sub>	A		32		
Primary current measuring range	I <sub>pm</sub>	A	-80		80	
Supply voltage	V <sub>cc</sub>	V	4.75	5	5.25	
Current consumption	I <sub>cc</sub>	mA		5	10	
Reference voltage	V <sub>ref</sub>	V	2.48	2.5	2.52	Output function
Rated output voltage	V <sub>FS</sub>	V		0.8		(V <sub>out</sub> - V <sub>ref</sub> ) @ I <sub>pn</sub>
Internal output resistance	R <sub>out</sub>	Ω		1		Output
Internal output resistance	R <sub>ref</sub>	Ω		1		Output
Quiescent voltage	V <sub>off</sub>	V	2.48	2.5	2.52	V <sub>out</sub> @ 0 A
Electrical offset voltage	V <sub>oe</sub>	mV	-10		10	(V <sub>out</sub> - V <sub>ref</sub> ) @ 0 A
Temperature drift of V <sub>oe</sub>	V <sub>oe</sub> _TRange	mV	-8		8	-40°C ~ 105°C
Magnetic offset current	I <sub>om</sub>	A	-0.25		0.25	@ ±10 x I <sub>pn</sub>
Theoretical gain	G <sub>th</sub>	mV/A		25		800 mV @ I <sub>pn</sub>
Error of gain	Err <sub>G</sub>	%G <sub>th</sub>		±0.5		Trimmed in the factory @ 25°C
Temperature drift of gain	G <sub>TR</sub>	%G <sub>th</sub>	-1.0		1.0	-40°C ~ 105°C
Rated linearity error	Non-L <sub>pn</sub>	%I <sub>pn</sub>	-0.5		0.5	±I <sub>pn</sub>
Linearity error @ I <sub>pm</sub>	Non-L <sub>pm</sub>	%I <sub>pm</sub>	-1.0		1.0	±I <sub>pm</sub>
Reaction time	t <sub>ra</sub>	μs		0.1	0.2	@ 10% of I <sub>pn</sub>
Step response time	t <sub>res</sub>	μs		0.2	0.5	@ 90% of I <sub>pn</sub>
Delay time	t <sub>delay</sub>	μs		0.2		1000kHz sine wave
Frequency bandwidth (-3dB)	BW	kHz		1000		No RC circuit
Output voltage noise	V <sub>noise</sub>	mVpp		12		
DC ~ 10 kHz				17		
DC ~ 100 kHz						
Accuracy @ 25°C	X	% of I <sub>pn</sub>	-1		1	@ 25°C
Accuracy @ -40°C ~ 105°C	X_TRange	% of I <sub>pn</sub>	-2		2	-40°C ~ 105°C

## 5. STK-40PL/AG Electrical performance

Condition:  $T_A = 25^\circ\text{C}$   $V_{cc} = 5\text{ V}$  (Except special instructions)

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal current rms	$I_{pn}$	A		40		
Primary current measuring range	$I_{pm}$	A	-100		100	
Supply voltage	$V_{cc}$	V	4.75	5	5.25	
Current consumption	$I_{cc}$	mA		5	10	
Reference voltage	$V_{ref}$	V	2.48	2.5	2.52	Output function
Rated output voltage	$V_{FS}$	V		0.8		$(V_{out} - V_{ref}) @ I_{pn}$
Internal output resistance	$R_{out}$	$\Omega$		1		Output
Internal output resistance	$R_{ref}$	$\Omega$		1		Output
Quiescent voltage	$V_{off}$	V	2.48	2.5	2.52	$V_{out} @ 0\text{ A}$
Electrical offset voltage	$V_{oe}$	mV	-10		10	$(V_{out} - V_{ref}) @ 0\text{ A}$
Temperature drift of $V_{oe}$	$V_{oe\_TRange}$	mV	-8		8	$-40^\circ\text{C} \sim 105^\circ\text{C}$
Magnetic offset current	$I_{om}$	A	-0.25		0.25	@ $\pm 10 \times I_{pn}$
Theoretical gain	$G_{th}$	mV/A		20		800 mV @ $I_{pn}$
Error of gain	$Err\_G$	% $G_{th}$		$\pm 0.5$		Trimmed in the factory @ $25^\circ\text{C}$
Temperature drift of gain	$G_{TR}$	% $G_{th}$	-1.0		1.0	$-40^\circ\text{C} \sim 105^\circ\text{C}$
Rated linearity error	$Non-L_{pn}$	% $I_{pn}$	-0.5		0.5	$\pm I_{pn}$
Linearity error @ $I_{pm}$	$Non-L_{pm}$	% $I_{pm}$	-1		1	$\pm I_{pm}$
Reaction time	$t_{ra}$	$\mu\text{s}$		0.1	0.2	@ 10% of $I_{pn}$
Step response time	$t_{res}$	$\mu\text{s}$		0.2	0.5	@ 90% of $I_{pn}$
Delay time	$t_{delay}$	$\mu\text{s}$		0.2		1000kHz sine wave
Frequency bandwidth (-3dB)	BW	kHz		1000		No RC circuit
Output voltage noise	$V_{noise}$	mVpp		10		
DC ~ 10 kHz				15		
Accuracy @ $25^\circ\text{C}$	X	% of $I_{pn}$	-1		1	@ $25^\circ\text{C}$
Accuracy @ $-40^\circ\text{C} \sim 105^\circ\text{C}$	$X_{TRange}$	% of $I_{pn}$	-2		2	$-40^\circ\text{C} \sim 105^\circ\text{C}$

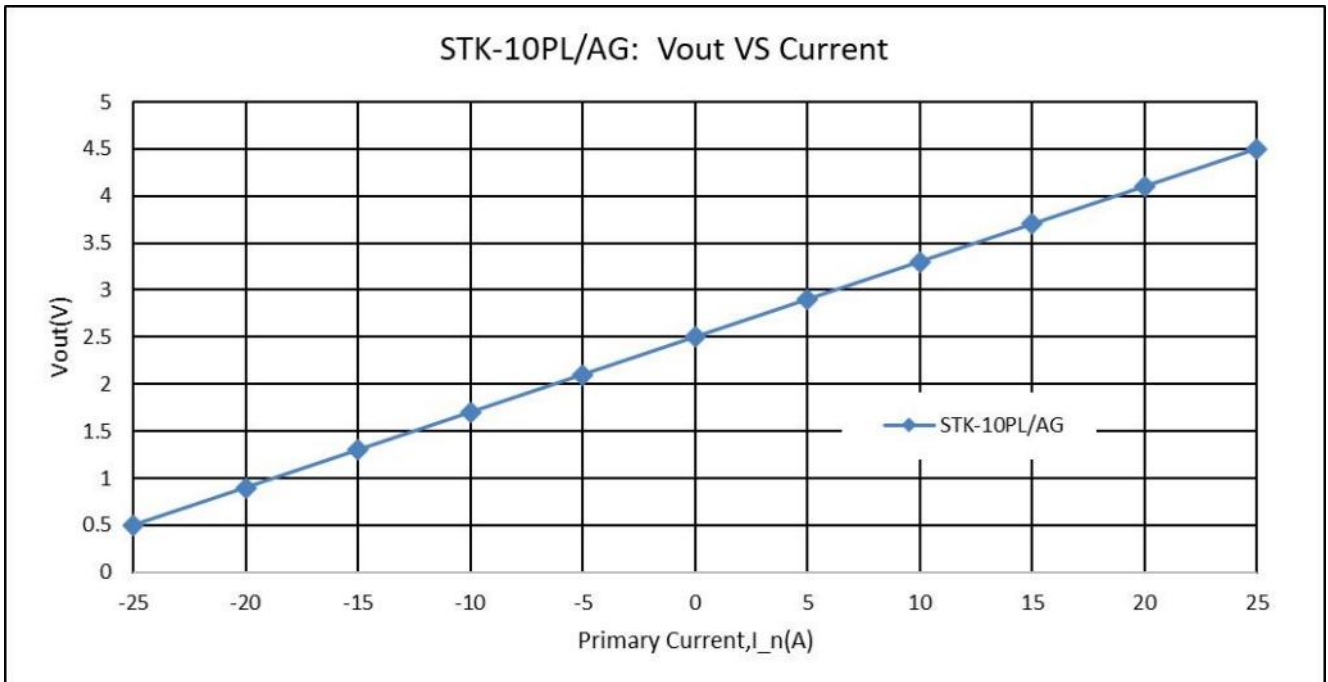


## 6. STK-50PL/AG Electrical performance

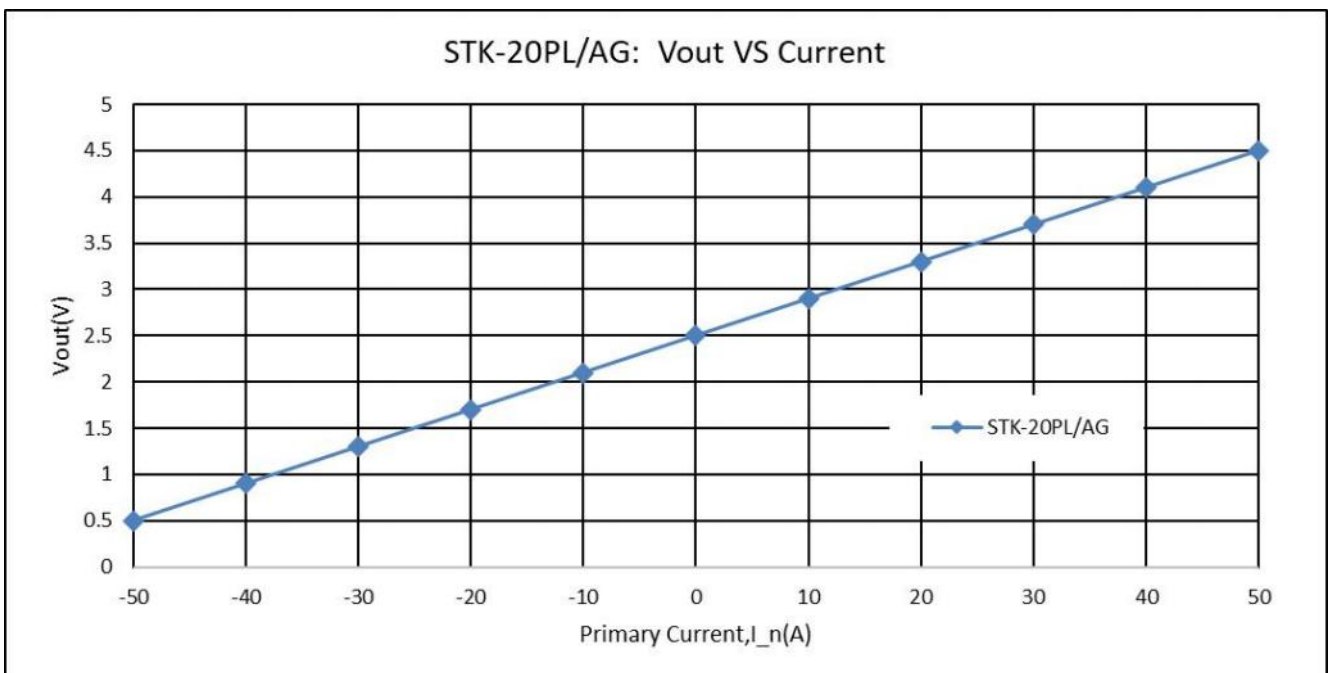
Condition:  $T_A = 25^\circ\text{C}$   $V_{cc} = 5\text{ V}$  (Except special instructions)

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Primary nominal current rms	$I_{pn}$	A		50		
Primary current measuring range	$I_{pm}$	A	-125		125	
Supply voltage	$V_{cc}$	V	4.75	5	5.25	
Current consumption	$I_{cc}$	mA		5	10	
Reference voltage	$V_{ref}$	V	2.48	2.5	2.52	Output function
Rated output voltage	$V_{FS}$	V		0.8		$(V_{out} - V_{ref}) @ I_{pn}$
Internal output resistance	$R_{out}$	$\Omega$		1		Output
Internal output resistance	$R_{ref}$	$\Omega$		1		Output
Quiescent voltage	$V_{off}$	V	2.48	2.5	2.52	$V_{out} @ 0\text{ A}$
Electrical offset voltage	$V_{oe}$	mV	-10		10	$(V_{out} - V_{ref}) @ 0\text{ A}$
Temperature drift of $V_{oe}$	$V_{oe\_TRange}$	mV	-8		8	$-40^\circ\text{C} \sim 105^\circ\text{C}$
Magnetic offset current	$I_{om}$	A	-0.25		0.25	@ $\pm 10 \times I_{pn}$
Theoretical gain	$G_{th}$	mV/A		16		800 mV @ $I_{pn}$
Error of gain	$Err\_G$	% $G_{th}$		$\pm 0.5$		Trimmed in the factory @ $25^\circ\text{C}$
Temperature drift of gain	$G_{TR}$	% $G_{th}$	-1.0		1.0	$-40^\circ\text{C} \sim 105^\circ\text{C}$
Rated linearity error	$Non-L_{pn}$	% $I_{pn}$	-0.5		0.5	$\pm I_{pn}$
Linearity error @ $I_{pm}$	$Non-L_{pm}$	% $I_{pm}$	-1.5		1.5	$\pm I_{pm}$
Reaction time	$t_{ra}$	$\mu\text{s}$		0.1	0.2	@ 10% of $I_{pn}$
Step response time	$t_{res}$	$\mu\text{s}$		0.2	0.5	@ 90% of $I_{pn}$
Delay time	$t_{delay}$	$\mu\text{s}$		0.2		1000kHz sine wave
Frequency bandwidth (-3dB)	BW	kHz		1000		No RC circuit
Output voltage noise	$V_{noise}$	mVpp		10		
DC ~ 10 kHz				15		
DC ~ 100 kHz						
Accuracy @ $25^\circ\text{C}$	X	% of $I_{pn}$	-1		1	@ $25^\circ\text{C}$
Accuracy @ $-40^\circ\text{C} \sim 105^\circ\text{C}$	$X_{TRange}$	% of $I_{pn}$	-2		2	$-40^\circ\text{C} \sim 105^\circ\text{C}$

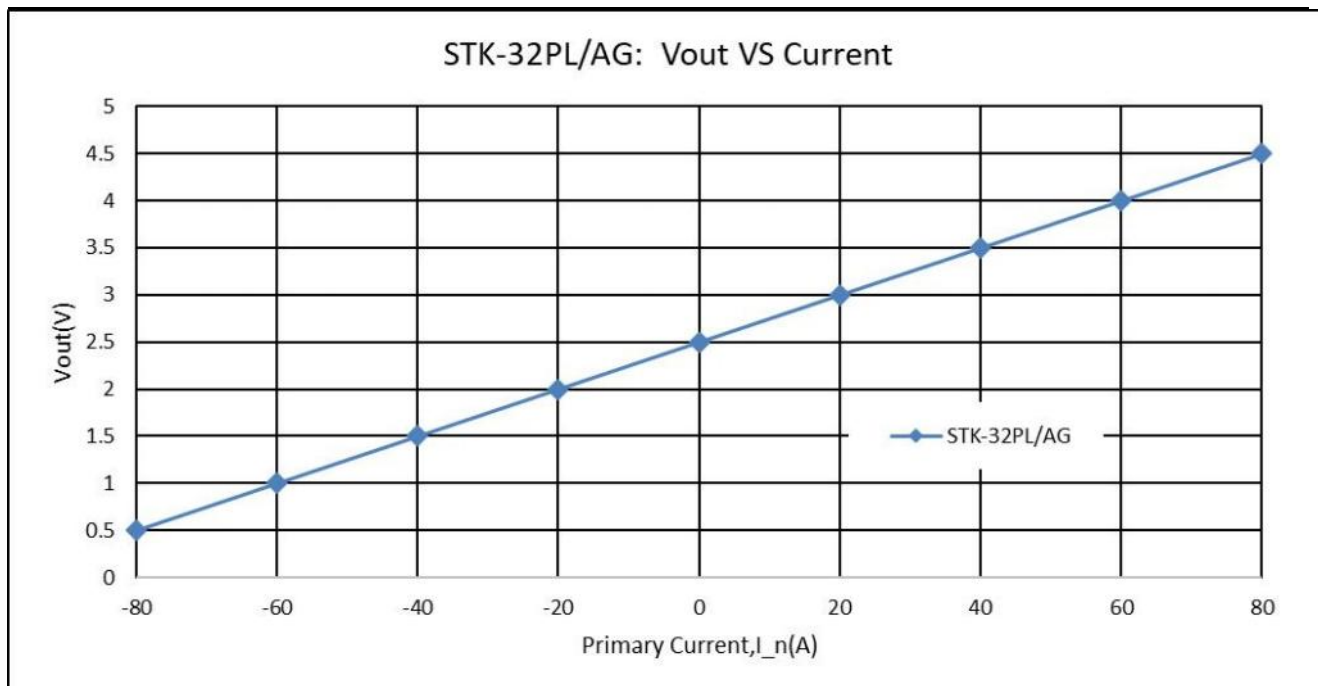
## 7. Output voltage VS primary current



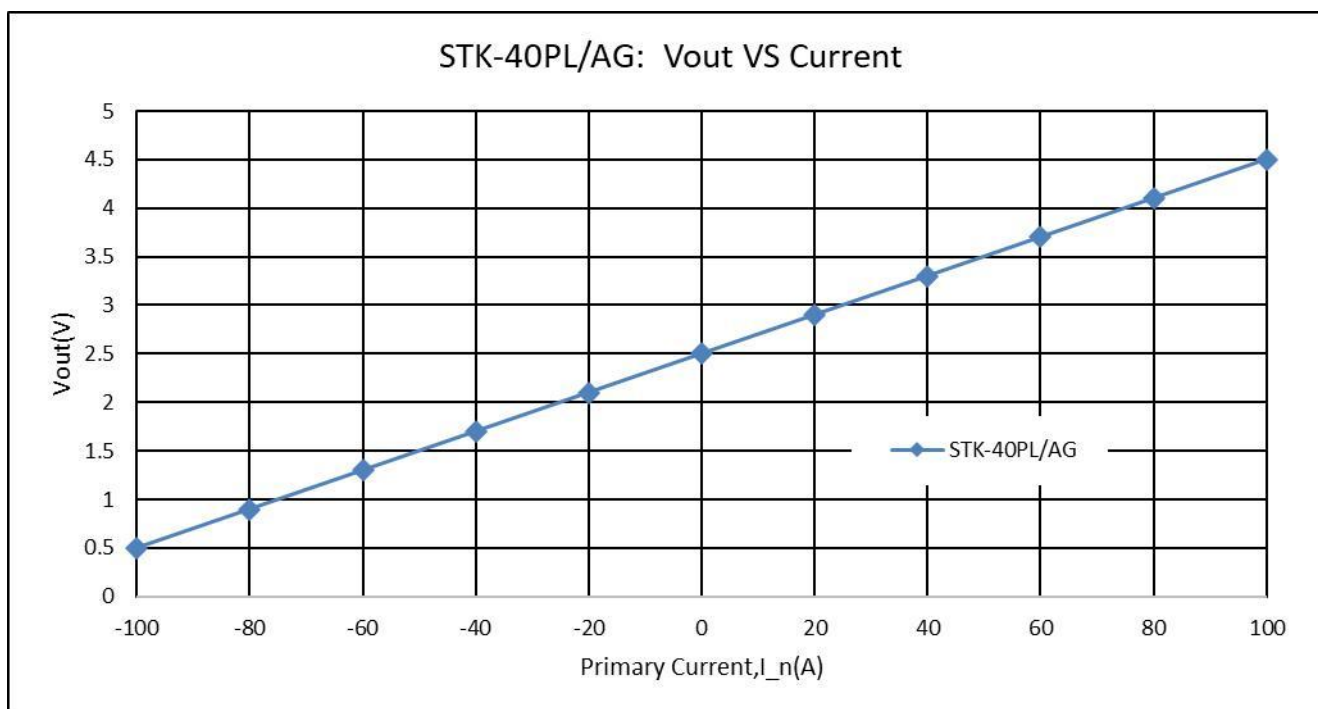
The dependence of Vout of STK-10PL/AG on the primary current.



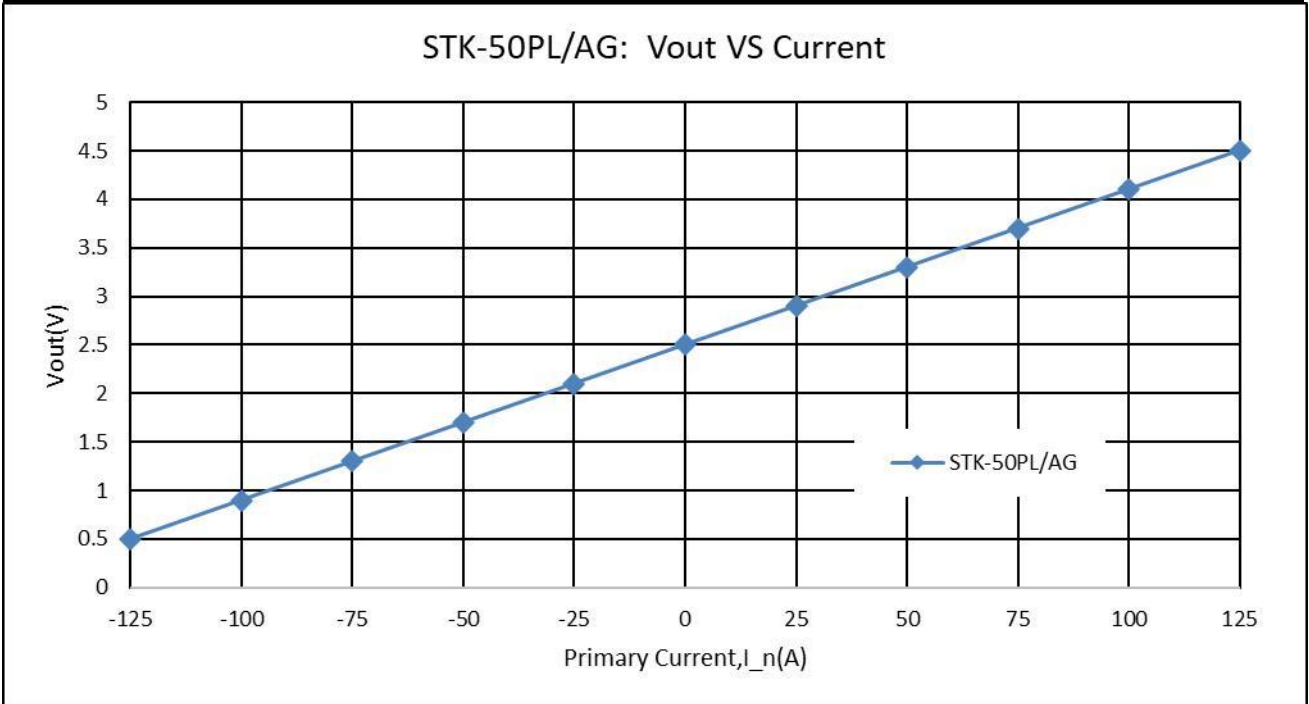
The dependence of Vout of STK-20PL/AG on the primary current.



The dependence of Vout of STK-32PL/AG on the primary current.

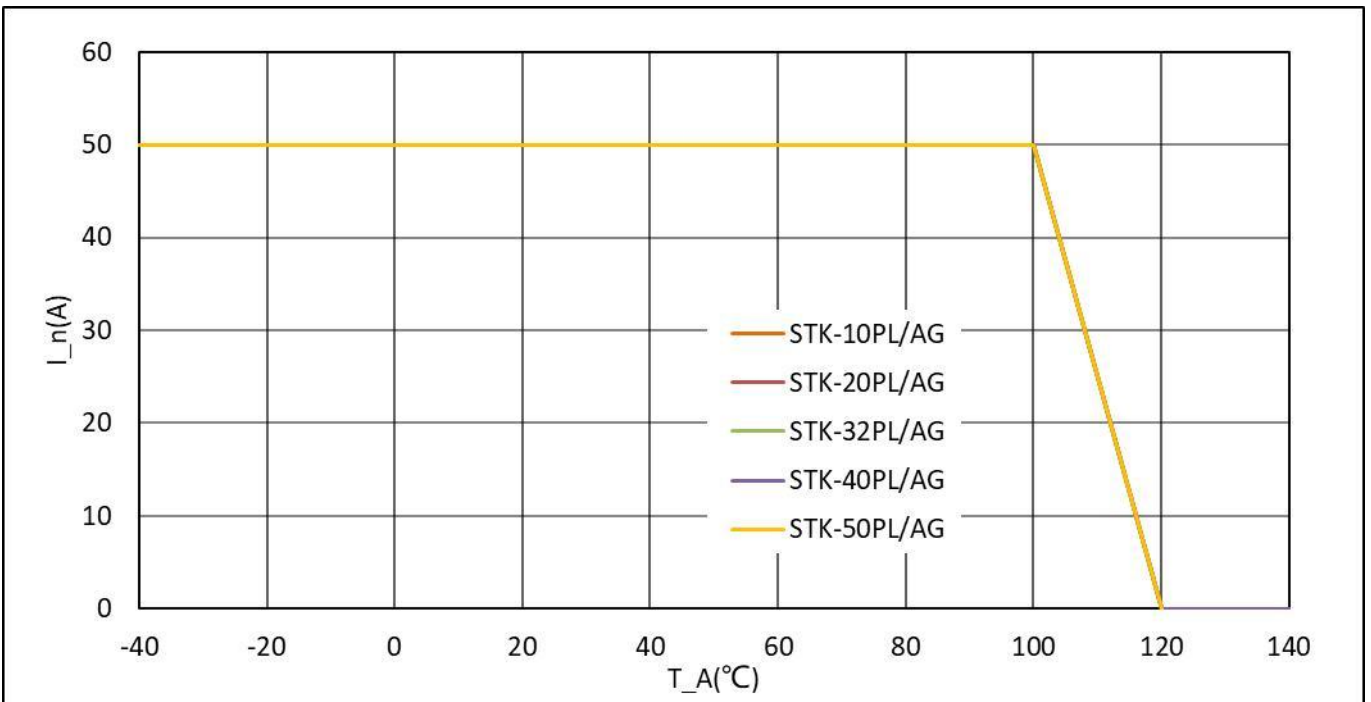


The dependence of Vout of STK-40PL/AG on the primary current.



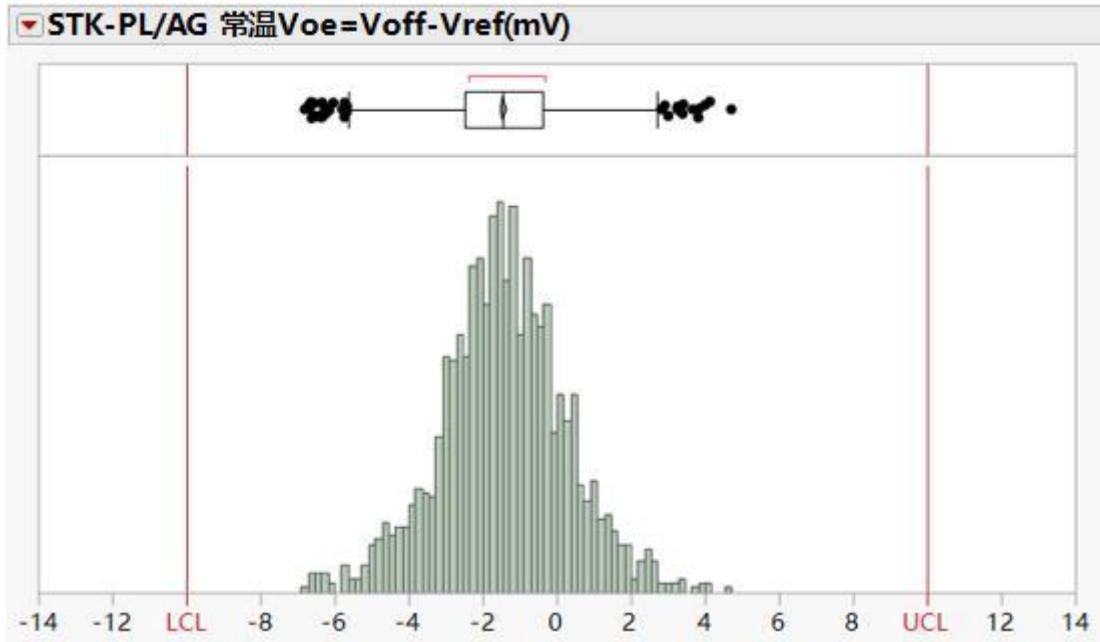
The dependence of Vout of STK-50PL/AG on the primary current.

## 8. Maximum continues DC current

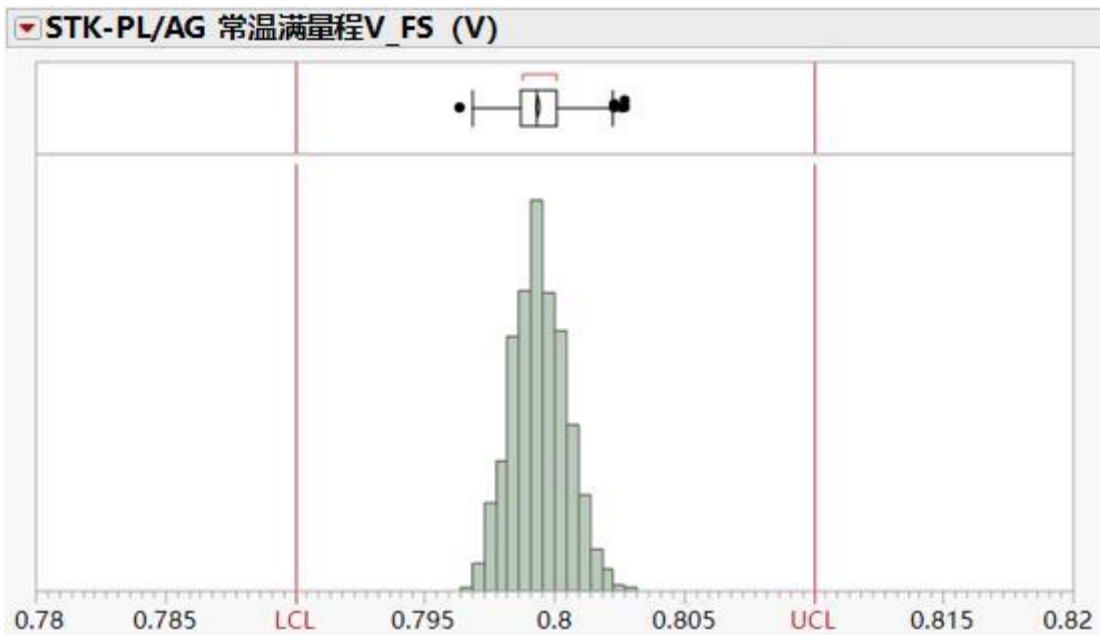


The dependence of maximum continues current of STK-PL/AG current on the working temperature.

## 9. Accuracy at room temperature

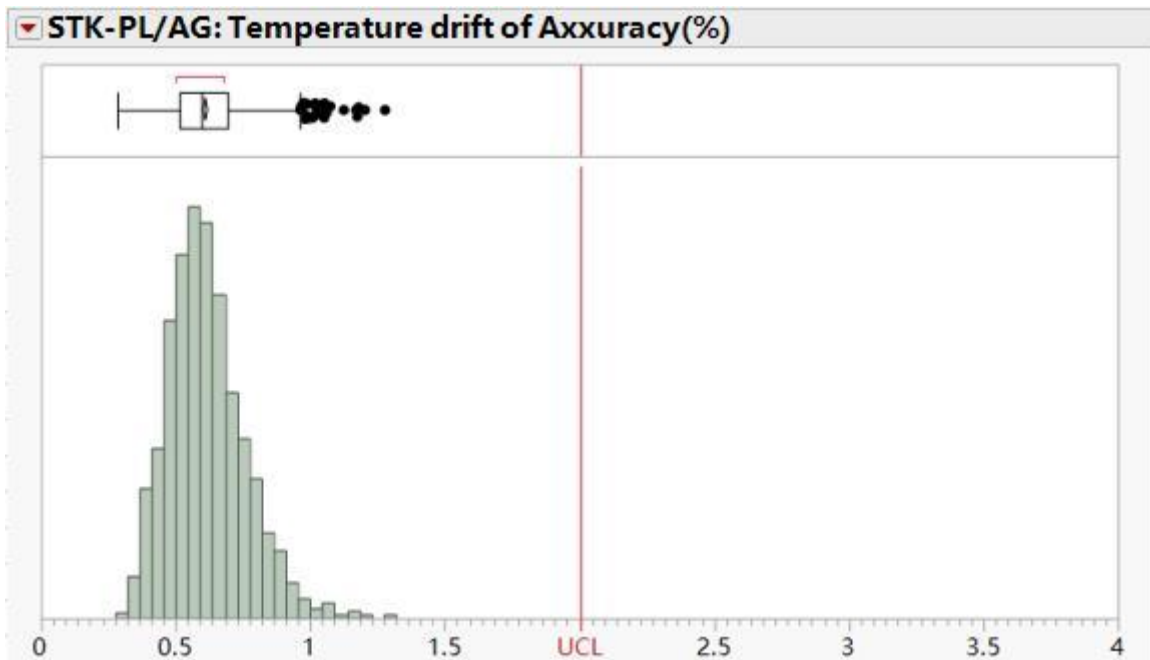


The distribution  $V_{oe}$  of STK-PL/AG current sensor at 25°C.

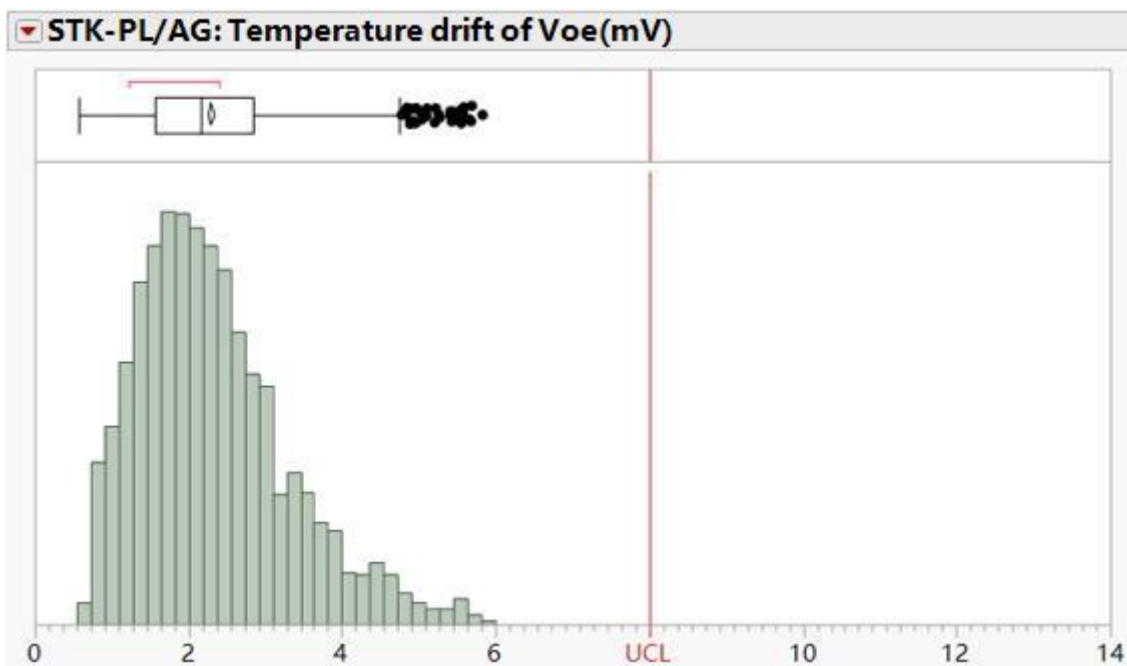


The distribution of  $V_{FS}$  OF STK-PL/AG current sensor at 25°C.

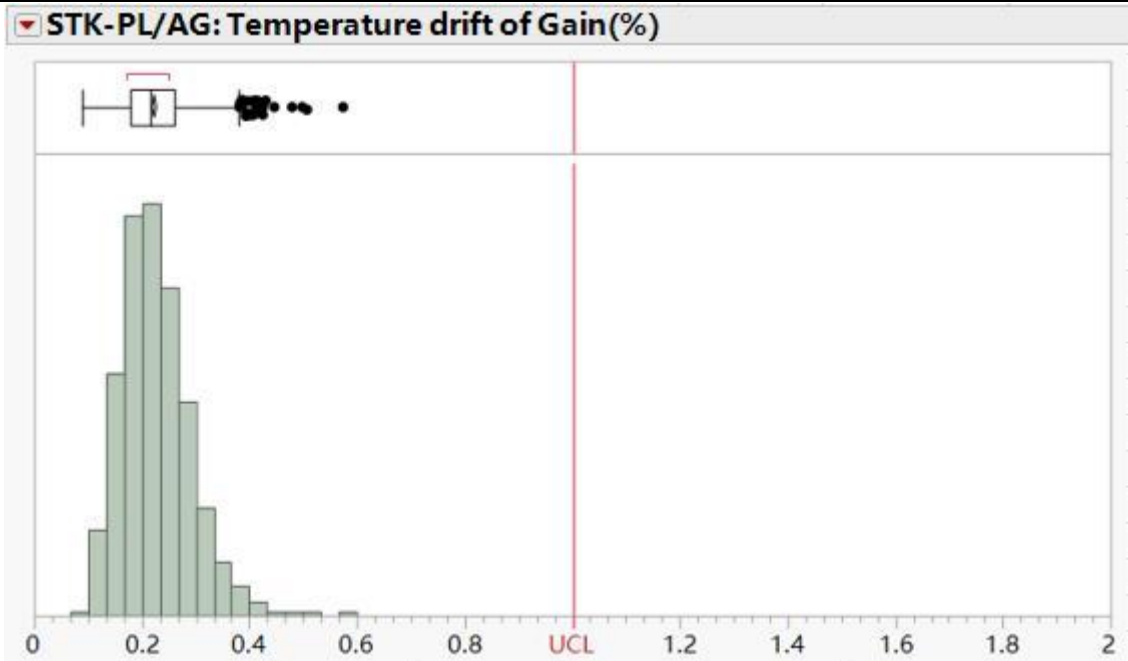
## 10. Accuracy over temperature



The distribution of temperature drift of accuracy, compared with room temperature, over the temperature range from -40 deg.C to 105 deg.C.

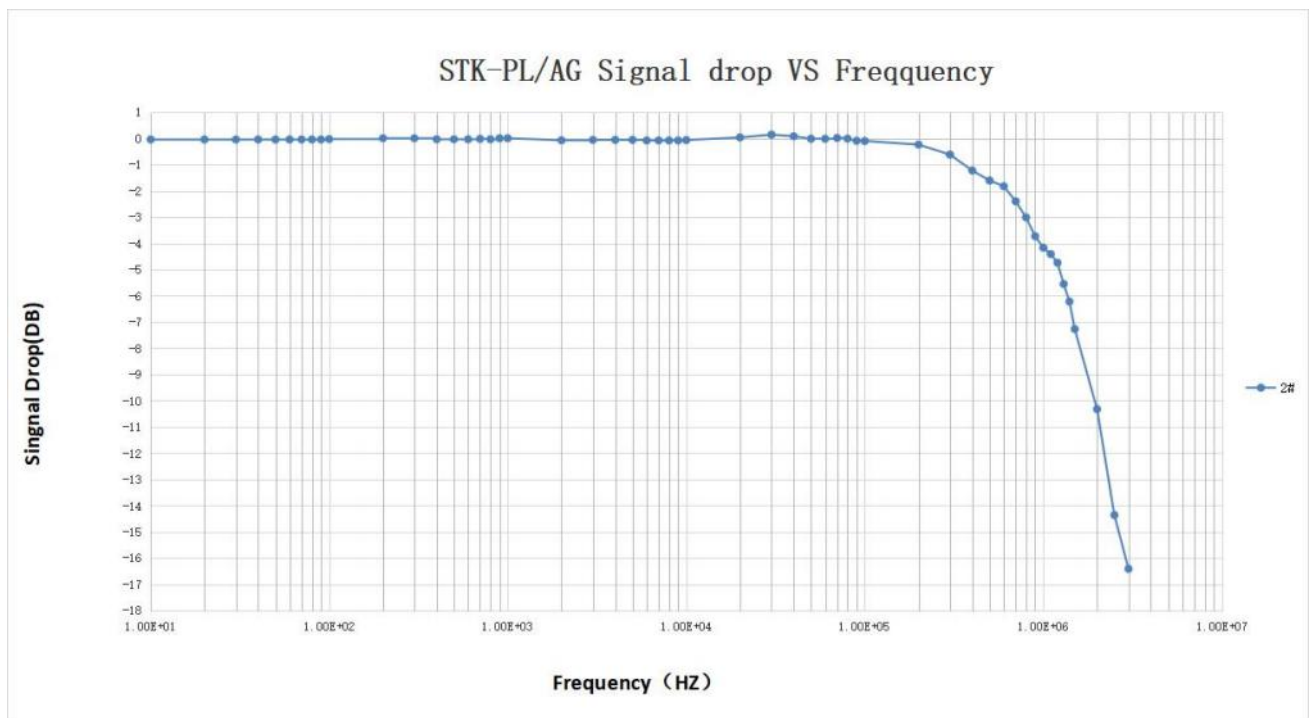


The distribution of temperature drift of Voe, compared with room temperature, over the temperature range from -40 deg.C to 105 deg.C.



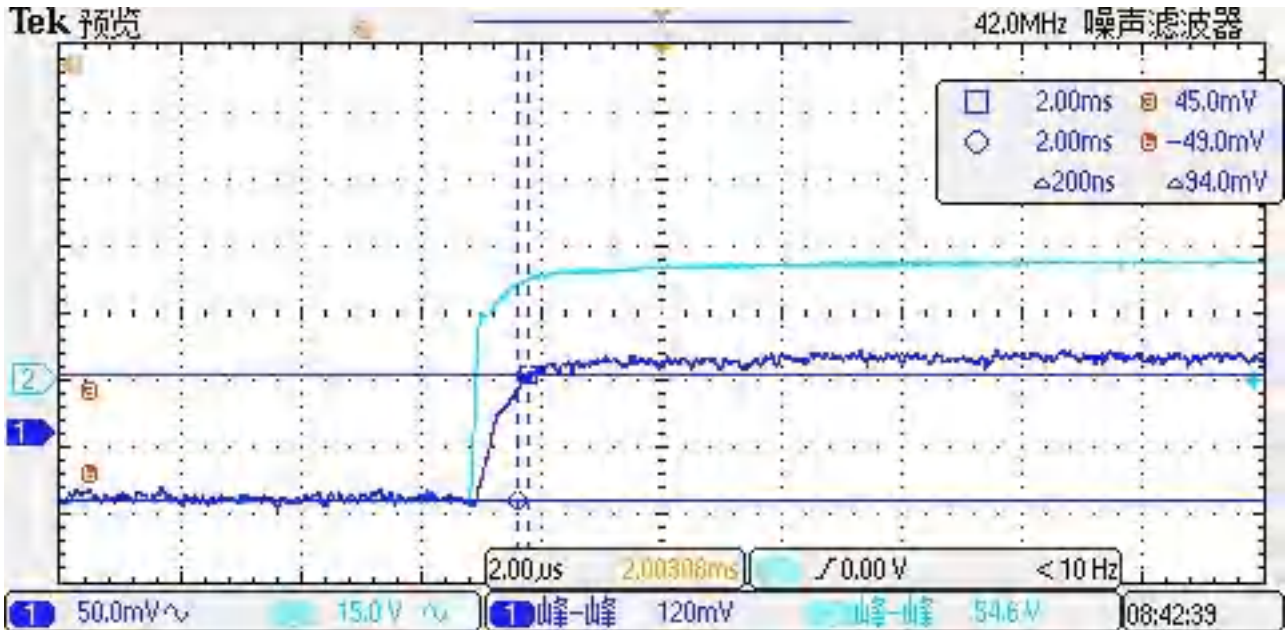
The distribution of temperature drift of GAIN, compared with room temperature, over the temperature range from -40 deg.C to 105 deg.C.

## 11. Frequency response and bandwidth



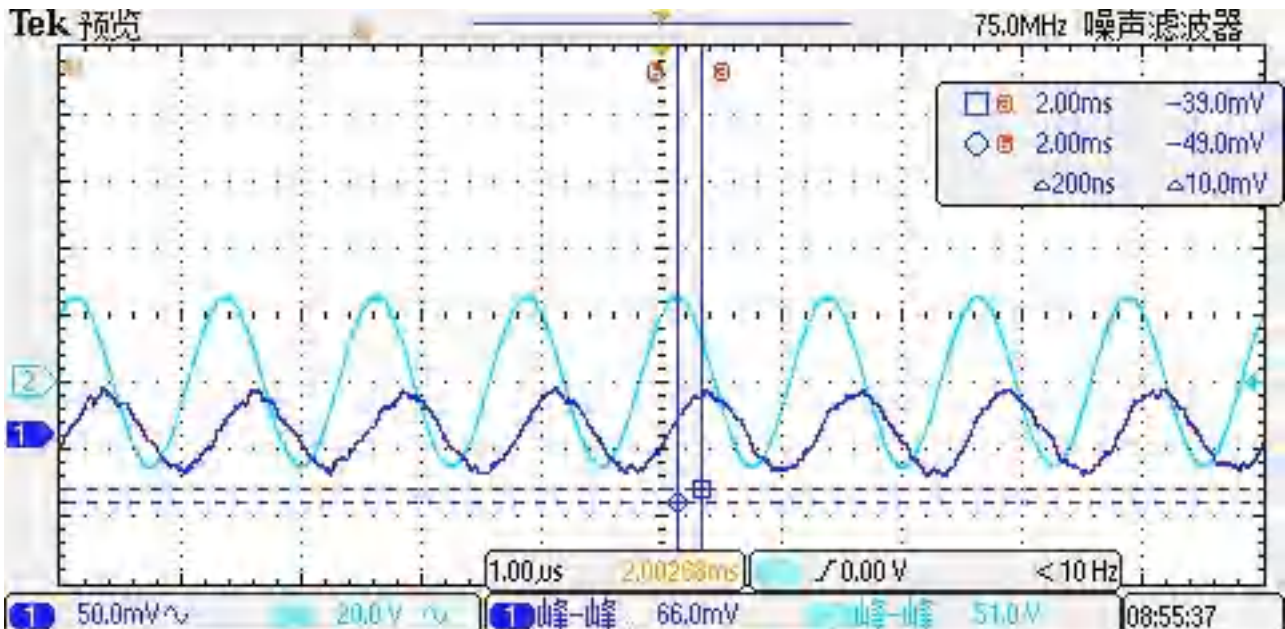
The frequency bandwidth of STK-PL/AG series current sensor. The bandwidth of current sensor is DC ~ 1000 kHz (-3dB).

## 12. Step response time



The typical frequency response of STK-xxPL/AG current sensor. The response time from 90% of the primary current (light blue) to 90% of the secondary output (dark blue) is less than 0.2  $\mu$ s

## 13. Frequency delay performance

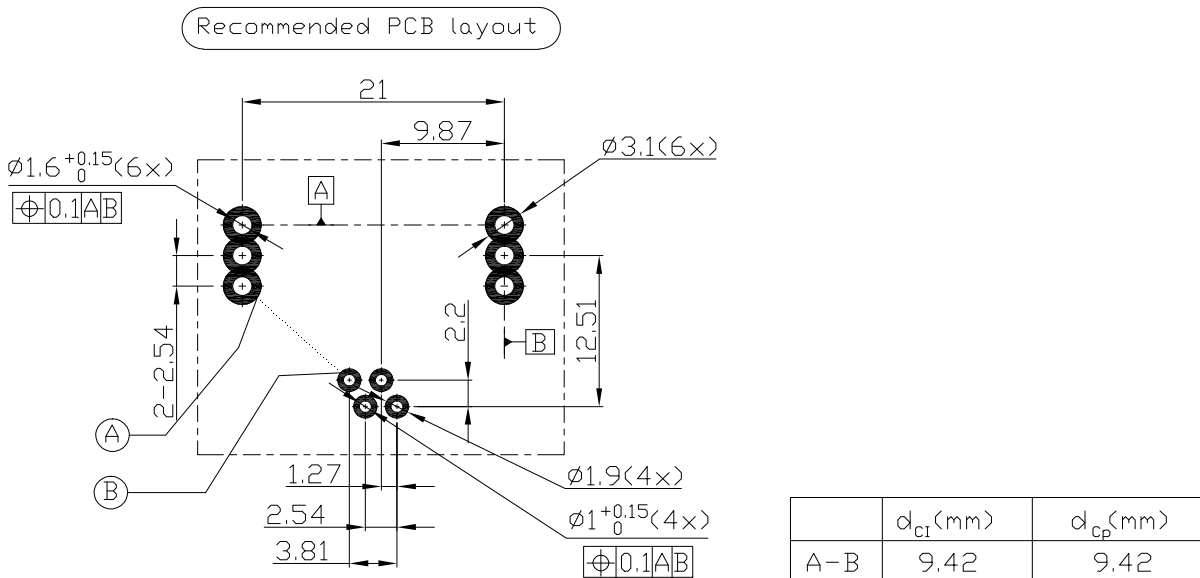


When testing 1000 kHz sine wave, the typical result of STK-xxPL/AG current sensor's output. The response time from the primary current (light blue) to the secondary output (dark blue) is less than 0.2  $\mu$ s.



## 14. Recommended PCB layout

Installation of view: overlooking (unit: mm)



1. Installing angle: Overlook (observe from the side of installing transducer)
2. Recommended bore diameter of primary current line, (diameter of primary current  $\times 1.2$ ) mm
3. Recommended bore diameter of secondary current line, (diameter of secondary current  $\times 1.2$ ) mm
4. The maximum thickness of PCB is 2.5 mm
5. The curve of wave soldering:  $260^{\circ}\text{C} \times 10 \text{ s}$

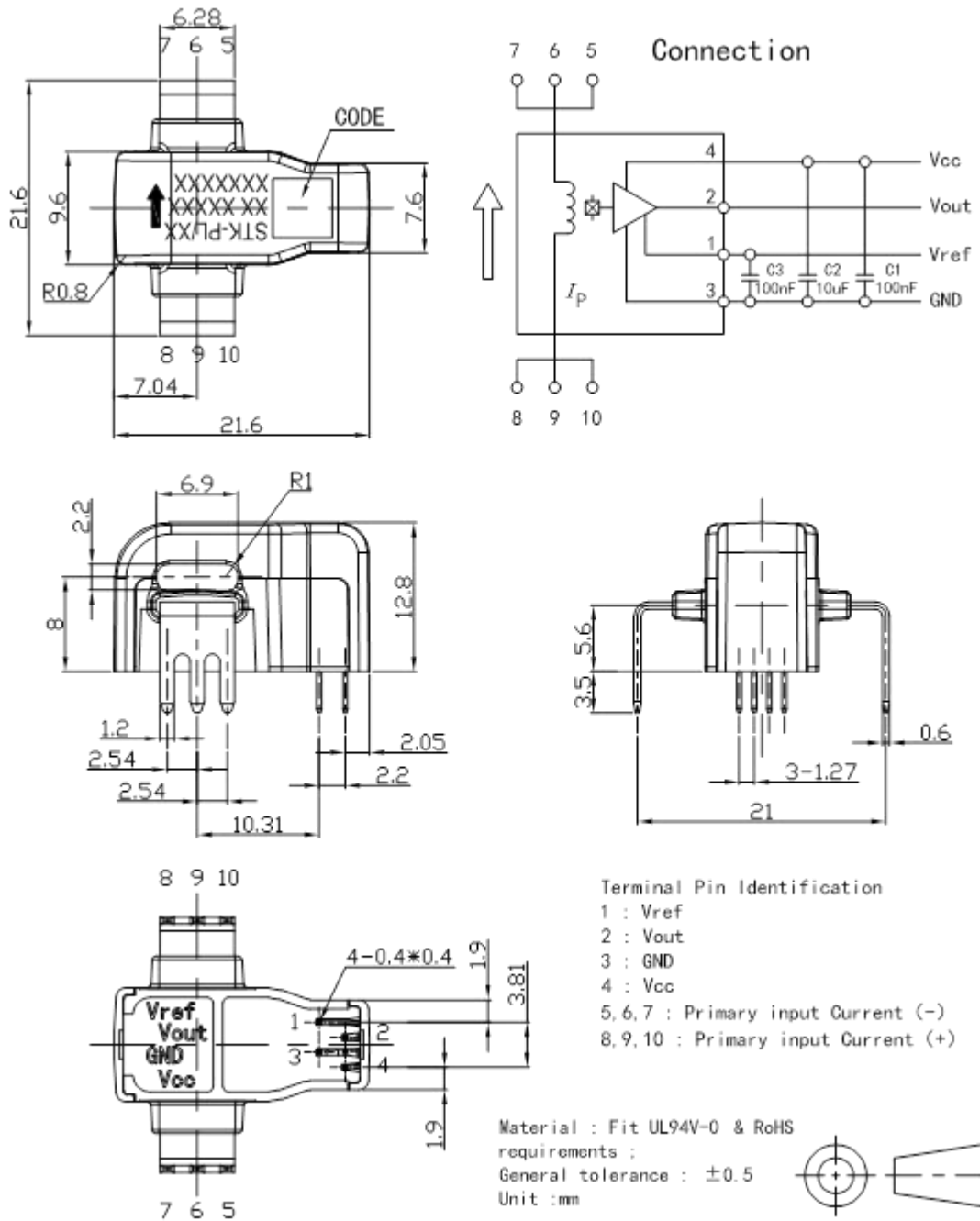


### Security:

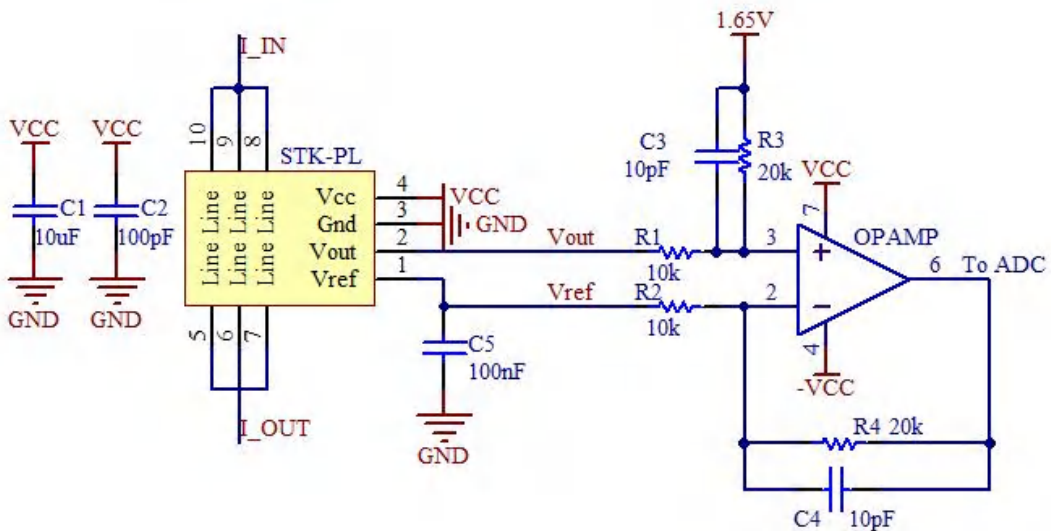
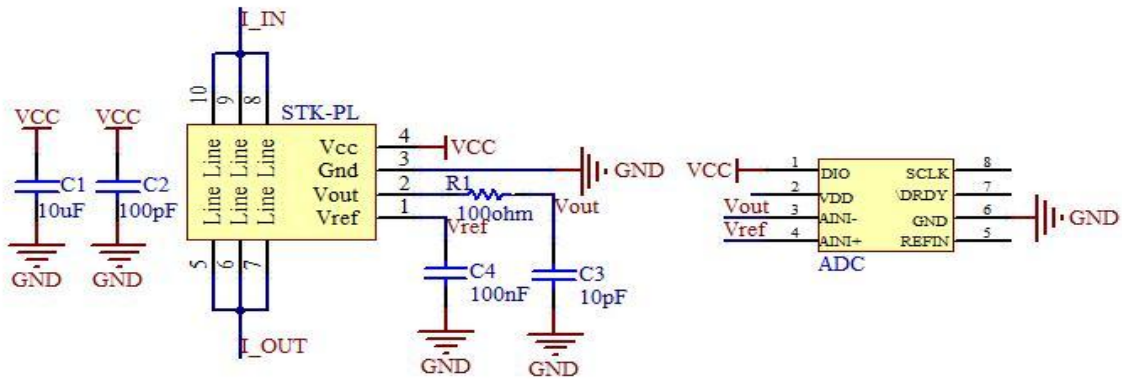
This current sensor must be used in limited-energy secondary circuit according to IEC 61010-1.

- This current sensor must be used in electric/electronic equipment with respect to appliance standards and safety requirement in accordance with the manufacture's operating instructions;
- When operating the current sensor, certain parts of the module can carry hazardous voltage;
- Failure to wiring as shown in the diagram will damage the current sensor;
- Ignoring this warning can lead to serious consequences.
- A protective housing or a additional shield could be used.
- Main supply must be able to disconnected.

## 15. Dimension & Pin definitions



## 16. Appendix: typical application circuit



R3 (kohm)	C3 (pF)	Theoretical -3dB $f = 1/(2\pi RC)$ (kHz)	Measured -3dB (kHz)
20	20	998	~ 1000
20	81	98	~ 100
20	810	10	~ 10

The frequency characteristics of STK\_PL/AG series current sensor are not affected by the R-C setting (according to recommended R-C setting), therefore the active filter circuit or R-C circuit can be applied to modulate the sensor's frequency characteristics.

The signal input to ADC is  $1.65 + R4/R2 * (Vout - Vref)$  with the conditions:  $R1 = R2, R3 = R4, C3 = C4$ .